

Boundaries and interfaces in asymptotics of hyperbolic systems of balance laws

Nicolas Seguin

Laboratoire Jacques-Louis Lions, UPMC–Paris 6 (France)
Équipe–projet Ange, Inria Paris–Rocquencourt

LRC Manon, CEA/DM2S–LJLL
UPMC/Emergence project on kidney modeling

KI-Net conference:

Asymptotic preserving and multiscale methods for kinetic and hyperbolic problems
University of Wisconsin-Madison, May 4–8, 2015

Boundaries and interfaces in asymptotics of hyperbolic systems of balance laws

Hyperbolic systems of balance laws with stiff effects

- hyperbolic limit
- parabolic limit

Pointwise effects and small layers

- Boundary conditions
- Coupling interfaces

Boundaries and interfaces in asymptotics of hyperbolic systems of balance laws

Two distinct problems:

I. Jin–Xin model with implicit equilibrium manifold on a bounded domain

- Asymptotic behavior of boundary conditions
- Approximate but explicit computation of the equilibrium manifold

with B. Perthame and M. Tournus

II. Interface coupling of a systems of balance laws with its parabolic limit

- The Goldstein–Taylor model and the heat equation
- The p -system and the nonlinear heat equation
- Interface coupling/domain decomposition/two-scale discontinuous rate

with A.-C. Boulanger, C. Cancès, H. Mathis and K. Saleh

Jin–Xin model with implicit equilibrium manifold

U-tube with porous walls (from kidney modeling):

$$\begin{cases} \partial_t u_\varepsilon + \partial_x u_\varepsilon = \frac{1}{\varepsilon} (h(v_\varepsilon) - u_\varepsilon) \\ \partial_t v_\varepsilon - \partial_x v_\varepsilon = \frac{1}{\varepsilon} (u_\varepsilon - h(v_\varepsilon)) \end{cases} \quad \text{on } [0, 1]$$

$$\text{BC's: } u_\varepsilon(t, 0) = u_l \quad \text{and} \quad v_\varepsilon(t, 1) = \alpha u_\varepsilon(t, 1) \quad (0 < \alpha \leq 1)$$

$$\text{and } \{h(v) = u\} \cap \{v = \alpha u\} = \emptyset$$

Two main difficulties

1. Asymptotic boundary conditions: numerical boundary layers
2. Implicit equilibrium manifold $\mathcal{E} = \{u = h(v)\}$

Assuming $h' > 1$, the limit $\varepsilon \rightarrow 0$ satisfies $u = h(v)$ and

$$\partial_t A(v) + \partial_x B(v) = 0$$

where

$$A(v) = h(v) + v \quad \text{and} \quad B(v) = h(v) - v$$

Jin–Xin model with implicit equilibrium manifold

U-tube with porous walls (from kidney modeling):

$$\begin{cases} \partial_t u_\varepsilon + \partial_x u_\varepsilon = \frac{1}{\varepsilon} (h(v_\varepsilon) - u_\varepsilon) \\ \partial_t v_\varepsilon - \partial_x v_\varepsilon = \frac{1}{\varepsilon} (u_\varepsilon - h(v_\varepsilon)) \end{cases} \quad \text{on } [0, 1]$$

$$\text{BC's: } u_\varepsilon(t, 0) = u_l \quad \text{and} \quad v_\varepsilon(t, 1) = \alpha u_\varepsilon(t, 1) \quad (0 < \alpha \leq 1)$$

$$\text{and } \{h(v) = u\} \cap \{v = \alpha u\} = \emptyset$$

Two main difficulties

1. Asymptotic boundary conditions: **numerical boundary layers**
2. **Implicit equilibrium manifold** $\mathcal{E} = \{u = h(v)\}$

Assuming $h' > 1$, the limit $\varepsilon \rightarrow 0$ satisfies $u = h(v)$ and

$$\partial_t A(v) + \partial_x B(v) = 0$$

where

$$A(v) = h(v) + v \quad \text{and} \quad B(v) = h(v) - v$$

Numerical boundary layers for the Jin–Xin model

The **classical** Jin–Xin model:

$$(JX) \quad \begin{cases} \partial_t a_\varepsilon + \partial_x b_\varepsilon = 0 \\ \partial_t b_\varepsilon + \partial_x a_\varepsilon = \frac{1}{\varepsilon} (f(a_\varepsilon) - b_\varepsilon) \end{cases}$$

Assuming $0 < f' < 1$, the limit $\varepsilon \rightarrow 0$ satisfies

$$(CL) \quad \partial_t a + \partial_x f(a) = 0, \quad b = f(a)$$

Numerical approximation by a splitting technique

- Upwind scheme for the PDE part $(a_\varepsilon, b_\varepsilon)_i^n \rightarrow (a_\varepsilon, b_\varepsilon)_i^{n+1/2}$
- Implicit scheme with **explicit formula** $(a_\varepsilon, b_\varepsilon)_i^{n+1/2} \rightarrow (a_\varepsilon, b_\varepsilon)_i^{n+1}$

$$\begin{cases} (a_\varepsilon)_i^{n+1} = (a_\varepsilon)_i^{n+1/2}, \\ (b_\varepsilon)_i^{n+1} = (b_\varepsilon)_i^{n+1/2} + \frac{\Delta t}{\varepsilon} (f((a_\varepsilon)_i^{n+1}) - (b_\varepsilon)_i^{n+1}). \end{cases}$$

Numerical boundary layers for the Jin–Xin model

The **classical** Jin–Xin model:

$$(JX) \quad \begin{cases} \partial_t a_\varepsilon + \partial_x b_\varepsilon = 0 \\ \partial_t b_\varepsilon + \partial_x a_\varepsilon = \frac{1}{\varepsilon} (f(a_\varepsilon) - b_\varepsilon) \end{cases}$$

Assuming $0 < f' < 1$, the limit $\varepsilon \rightarrow 0$ satisfies

$$(CL) \quad \partial_t a + \partial_x f(a) = 0, \quad b = f(a)$$

Numerical approximation by a splitting technique

- Upwind scheme for the PDE part $(a_\varepsilon, b_\varepsilon)_i^n \rightarrow (a_\varepsilon, b_\varepsilon)_i^{n+1/2}$
- Implicit scheme with **explicit formula** $(a_\varepsilon, b_\varepsilon)_i^{n+1/2} \rightarrow (a_\varepsilon, b_\varepsilon)_i^{n+1}$

$$\begin{cases} (a_\varepsilon)_i^{n+1} = (a_\varepsilon)_i^{n+1/2}, \\ (b_\varepsilon)_i^{n+1} = (b_\varepsilon)_i^{n+1/2} + \frac{\Delta t}{\varepsilon} (f((a_\varepsilon)_i^{n+1}) - (b_\varepsilon)_i^{n+1}). \end{cases}$$

Numerical boundary layers for the Jin–Xin model

The **classical** Jin–Xin model:

$$(JX) \quad \begin{cases} \partial_t a_\varepsilon + \partial_x b_\varepsilon = 0 \\ \partial_t b_\varepsilon + \partial_x a_\varepsilon = \frac{1}{\varepsilon} (f(a_\varepsilon) - b_\varepsilon) \end{cases}$$

Assuming $0 < f' < 1$, the limit $\varepsilon \rightarrow 0$ satisfies

$$(CL) \quad \partial_t a + \partial_x f(a) = 0, \quad b = f(a)$$

Numerical approximation by a splitting technique

- Upwind scheme for the PDE part $(a_\varepsilon, b_\varepsilon)_i^n \rightarrow (a_\varepsilon, b_\varepsilon)_i^{n+1/2}$
- Implicit scheme with **explicit formula** $(a_\varepsilon, b_\varepsilon)_i^{n+1/2} \rightarrow (a_\varepsilon, b_\varepsilon)_i^{n+1}$

When $\varepsilon = 0$, it becomes the **Rusanov scheme** for (CL)

$$a_i^{n+1} = a_i^n - \frac{\Delta t}{2\Delta x} (f(a_{i+1}^n) - f(a_{i-1}^n) - (a_{i+1}^n - 2a_i^n + a_{i-1}^n))$$

Numerical boundary layers for the Jin–Xin model

Define $u_\varepsilon = a_\varepsilon + b_\varepsilon$ and $v_\varepsilon = a_\varepsilon - b_\varepsilon$ to decouple the PDE part:

$$(JXd) \quad \begin{cases} \partial_t u_\varepsilon + \partial_x u_\varepsilon = \frac{1}{\varepsilon} (f((u_\varepsilon + v_\varepsilon)/2) - (u_\varepsilon - v_\varepsilon)/2) \\ \partial_t v_\varepsilon - \partial_x v_\varepsilon = -\frac{1}{\varepsilon} ((u_\varepsilon - v_\varepsilon)/2 - f((u_\varepsilon + v_\varepsilon)/2)) \end{cases}$$

Bounded domain $[0, 1]$:

- Imposed entrance at $x = 0$:

$$u_\varepsilon(t, 0) = u_l$$

- Re-entrance at $x = 1$:

$$v_\varepsilon(t, 1) = \alpha u_\varepsilon(t, 1) \quad (\text{with } 0 < \alpha \leq 1)$$

Numerical boundary layers for the Jin–Xin model

Define $u_\varepsilon = a_\varepsilon + b_\varepsilon$ and $v_\varepsilon = a_\varepsilon - b_\varepsilon$ to decouple the PDE part:

$$\begin{cases} \partial_t u_\varepsilon + \partial_x u_\varepsilon = \frac{1}{\varepsilon} (f((u_\varepsilon + v_\varepsilon)/2) - (u_\varepsilon - v_\varepsilon)/2) \\ \partial_t v_\varepsilon - \partial_x v_\varepsilon = -\frac{1}{\varepsilon} ((u_\varepsilon - v_\varepsilon)/2 - f((u_\varepsilon + v_\varepsilon)/2)) \\ u_\varepsilon(t, 0) = u_l \quad \text{and} \quad v_\varepsilon(t, 1) = \alpha u_\varepsilon(t, 1) \end{cases}$$

Assuming $0 < f' < 1$, the limit $\varepsilon \rightarrow 0$ satisfies

$$\begin{cases} \partial_t a + \partial_x f(a) = 0 & \text{on } [0, 1] \\ [a + f(a)](t, 0) = u_l \end{cases}$$

At $x = 1$, presence of a relaxation boundary layer which vanishes as $\varepsilon \rightarrow 0$

Numerical boundary layers for the Jin–Xin model

Define $u_\varepsilon = a_\varepsilon + b_\varepsilon$ and $v_\varepsilon = a_\varepsilon - b_\varepsilon$ to decouple the PDE part:

$$\begin{cases} \partial_t u_\varepsilon + \partial_x u_\varepsilon = \frac{1}{\varepsilon} (f((u_\varepsilon + v_\varepsilon)/2) - (u_\varepsilon - v_\varepsilon)/2) \\ \partial_t v_\varepsilon - \partial_x v_\varepsilon = -\frac{1}{\varepsilon} ((u_\varepsilon - v_\varepsilon)/2 - f((u_\varepsilon + v_\varepsilon)/2)) \\ u_\varepsilon(t, 0) = u_l \quad \text{and} \quad v_\varepsilon(t, 1) = \alpha u_\varepsilon(t, 1) \end{cases}$$

Assuming $0 < f' < 1$, the limit $\varepsilon \rightarrow 0$ satisfies

$$\begin{cases} \partial_t a + \partial_x f(a) = 0 & \text{on } [0, 1] \\ [a + f(a)](t, 0) = u_l \end{cases}$$

At $x = 1$, presence of a relaxation boundary layer which vanishes as $\varepsilon \rightarrow 0$

Numerical boundary layers for the Jin–Xin model

Define $u_\varepsilon = a_\varepsilon + b_\varepsilon$ and $v_\varepsilon = a_\varepsilon - b_\varepsilon$ to decouple the PDE part:

$$\begin{cases} \partial_t u_\varepsilon + \partial_x u_\varepsilon = \frac{1}{\varepsilon} (f((u_\varepsilon + v_\varepsilon)/2) - (u_\varepsilon - v_\varepsilon)/2) \\ \partial_t v_\varepsilon - \partial_x v_\varepsilon = -\frac{1}{\varepsilon} ((u_\varepsilon - v_\varepsilon)/2 - f((u_\varepsilon + v_\varepsilon)/2)) \\ u_\varepsilon(t, 0) = u_l \quad \text{and} \quad v_\varepsilon(t, 1) = \alpha u_\varepsilon(t, 1) \end{cases}$$

Assuming $0 < f' < 1$, the limit $\varepsilon \rightarrow 0$ satisfies

$$\begin{cases} \partial_t a + \partial_x f(a) = 0 & \text{on } [0, 1] \\ [a + f(a)](t, 0) = u_l \end{cases}$$

At $x = 1$, presence of a **relaxation boundary layer** which vanishes as $\varepsilon \rightarrow 0$

Numerical boundary layers for the Jin–Xin model

From the **numerical** point of view:

- Boundary conditions approximated by ghost cells
- **But** the Rusanov scheme

$$a_i^{n+1} = a_i^n - \frac{\Delta t}{2\Delta x} (f(a_{i+1}^n) - f(a_{i-1}^n) - (a_{i+1}^n - 2a_i^n + a_{i-1}^n))$$

also introduces a **numerical boundary layer**

→ **Bad numerical approximation of the relaxation boundary layer**

Idea. Modify the numerical scheme in order to obtain the upwind scheme

$$a_i^{n+1} = a_i^n - \frac{\Delta t}{\Delta x} (f(a_i^n) - f(a_{i-1}^n))$$

Solution. See [Chalons, Berthon, Turpault 2013]: convex combination w.r.t. ε

Numerical boundary layers for the Jin–Xin model

From the **numerical** point of view:

- Boundary conditions approximated by ghost cells
- **But** the Rusanov scheme

$$a_i^{n+1} = a_i^n - \frac{\Delta t}{2\Delta x} (f(a_{i+1}^n) - f(a_{i-1}^n) - (a_{i+1}^n - 2a_i^n + a_{i-1}^n))$$

also introduces a **numerical boundary layer**

→ **Bad numerical approximation of the relaxation boundary layer**

Idea. Modify the numerical scheme in order to obtain the upwind scheme

$$a_i^{n+1} = a_i^n - \frac{\Delta t}{\Delta x} (f(a_i^n) - f(a_{i-1}^n))$$

Solution. See [Chalons, Berthon, Turpault 2013]: convex combination w.r.t. ε

Jin–Xin model with implicit equilibrium manifold

Jin–Xin model with implicit equilibrium manifold:

$$(IJX) \quad \begin{cases} \partial_t u_\varepsilon + \partial_x u_\varepsilon = \frac{1}{\varepsilon} (h(v_\varepsilon) - u_\varepsilon) \\ \partial_t v_\varepsilon - \partial_x v_\varepsilon = \frac{1}{\varepsilon} (u_\varepsilon - h(v_\varepsilon)) \end{cases}$$

Assuming $h' > 1$, the limit $\varepsilon \rightarrow 0$ satisfies $u = h(v)$ and

$$(ICL) \quad \partial_t A(v) + \partial_x B(v) = 0$$

where $A(v) = h(v) + v$ and $B(v) = h(v) - v$

Alternative formulation:

$$\begin{cases} a_\varepsilon = u_\varepsilon + v_\varepsilon \\ b_\varepsilon = u_\varepsilon - v_\varepsilon \end{cases} \implies \begin{cases} \partial_t a_\varepsilon + \partial_x b_\varepsilon = 0 \\ \partial_t b_\varepsilon + \partial_x a_\varepsilon = \frac{2}{\varepsilon} (h(a_\varepsilon - b_\varepsilon) - (a_\varepsilon + b_\varepsilon)) \end{cases}$$

Assuming $h' > 1$, the limit $\varepsilon \rightarrow 0$ satisfies $a + b = h(a - b)$ and

$$\partial_t a + \partial_x C(a) = 0$$

where $C(a) = B \circ A^{-1}(a)$

Jin–Xin model with implicit equilibrium manifold

Jin–Xin model with implicit equilibrium manifold:

$$(IJX) \quad \begin{cases} \partial_t u_\varepsilon + \partial_x u_\varepsilon = \frac{1}{\varepsilon} (h(v_\varepsilon) - u_\varepsilon) \\ \partial_t v_\varepsilon - \partial_x v_\varepsilon = \frac{1}{\varepsilon} (u_\varepsilon - h(v_\varepsilon)) \end{cases}$$

Assuming $h' > 1$, the limit $\varepsilon \rightarrow 0$ satisfies $u = h(v)$ and

$$(ICL) \quad \partial_t A(v) + \partial_x B(v) = 0$$

where $A(v) = h(v) + v$ and $B(v) = h(v) - v$

Alternative formulation:

$$\begin{cases} a_\varepsilon = u_\varepsilon + v_\varepsilon \\ b_\varepsilon = u_\varepsilon - v_\varepsilon \end{cases} \implies \begin{cases} \partial_t a_\varepsilon + \partial_x b_\varepsilon = 0 \\ \partial_t b_\varepsilon + \partial_x a_\varepsilon = \frac{2}{\varepsilon} (h(a_\varepsilon - b_\varepsilon) - (a_\varepsilon + b_\varepsilon)) \end{cases}$$

Assuming $h' > 1$, the limit $\varepsilon \rightarrow 0$ satisfies $a + b = h(a - b)$ and

$$\partial_t a + \partial_x C(a) = 0$$

where $C(a) = B \circ A^{-1}(a)$

Jin–Xin model with implicit equilibrium manifold

Whatever the formulation we choose:

- The limit equation requires to invert $A = h + \mathbf{I}$
- The usual splitting method for (IJX) also needs to **invert a nonlinear function**:

$$(b_\varepsilon)^{n+1} = (b_\varepsilon)^{n+1/2} + \frac{2\Delta t}{\varepsilon} (h((a_\varepsilon)^{n+1} - (b_\varepsilon)^{n+1}) - ((a_\varepsilon)^{n+1} + (b_\varepsilon)^{n+1}))$$

Construct a new numerical scheme for (IJX):

- which does not require any inversion of nonlinear functions
- which is a 3-point scheme
- which corresponds to the upwind scheme for the PDE part of (IJX)
- which becomes an upwind scheme for the limit equation (ICL)

Jin–Xin model with implicit equilibrium manifold

Whatever the formulation we choose:

- The limit equation requires to invert $A = h + \mathbf{I}$
- The usual splitting method for (IJX) also needs to **invert a nonlinear function**:

$$(b_\varepsilon)^{n+1} = (b_\varepsilon)^{n+1/2} + \frac{2\Delta t}{\varepsilon} (h((a_\varepsilon)^{n+1} - (b_\varepsilon)^{n+1}) - ((a_\varepsilon)^{n+1} + (b_\varepsilon)^{n+1}))$$

Construct a new numerical scheme for (IJX):

- which does not require any inversion of nonlinear functions
- which is a 3-point scheme
- which corresponds to the upwind scheme for the PDE part of (IJX)
- which becomes an upwind scheme for the limit equation (ICL)

Jin–Xin model with implicit equilibrium manifold

Whatever the formulation we choose:

- The limit equation requires to invert $A = h + \mathbf{I}$
- The usual splitting method for (IJX) also needs to **invert a nonlinear function**:

$$(b_\varepsilon)^{n+1} = (b_\varepsilon)^{n+1/2} + \frac{2\Delta t}{\varepsilon} (h((a_\varepsilon)^{n+1} - (b_\varepsilon)^{n+1}) - ((a_\varepsilon)^{n+1} + (b_\varepsilon)^{n+1}))$$

Construct a new numerical scheme for (IJX):

- which does not require any inversion of nonlinear functions
- which is a 3-point scheme
- which corresponds to the upwind scheme for the PDE part of (IJX)
- **which becomes an upwind scheme for the limit equation (ICL)**

Jin–Xin model with implicit equilibrium manifold

Construct a new numerical scheme for (IJX):

- which does not require any inversion of nonlinear functions
- which is a 3-point scheme
- which corresponds to the upwind scheme for the PDE part of (IJX)
- **which becomes an upwind scheme for the limit equation (ICL)**

[S., Tournus 2015]

Construction of a class of such schemes, for instance:

$$(IAP) \quad \begin{cases} (u_\varepsilon)_i^{n+1} = (u_\varepsilon)_i^n - \frac{\Delta t}{\Delta x} ((u_\varepsilon)_i^n - (u_\varepsilon)_{i-1}^n) + \frac{\Delta t}{\varepsilon + \Delta x} (S_{u_\varepsilon})_i^n \\ (v_\varepsilon)_i^{n+1} = (v_\varepsilon)_i^n + \frac{\Delta t}{\Delta x} ((v_\varepsilon)_{i+1}^n - (v_\varepsilon)_i^n) - \frac{\Delta t}{\varepsilon + \Delta x} (S_{v_\varepsilon})_i^n \end{cases}$$

where

$$\begin{cases} (S_{u_\varepsilon})_i^n = h((v_\varepsilon)_{i-1}^n) - (u_\varepsilon)_{i-1}^n + (v_\varepsilon)_i^n - (v_\varepsilon)_{i-1}^n \\ (S_{v_\varepsilon})_i^n = h((v_\varepsilon)_i^n) - (u_\varepsilon)_i^n + (v_\varepsilon)_{i+1}^n - (v_\varepsilon)_i^n \end{cases}$$

Jin–Xin model with implicit equilibrium manifold

Construct a new numerical scheme for (IJX):

- which does not require any inversion of nonlinear functions
- which is a 3-point scheme
- which corresponds to the upwind scheme for the PDE part of (IJX)
- which becomes an upwind scheme for the limit equation (ICL)

[S., Tournus 2015]

Construction of a class of such schemes, for instance:

$$(IAP) \quad \begin{cases} (u_\varepsilon)_i^{n+1} = (u_\varepsilon)_i^n - \frac{\Delta t}{\Delta x} ((u_\varepsilon)_i^n - (u_\varepsilon)_{i-1}^n) + \frac{\Delta t}{\varepsilon + \Delta x} (S_{u_\varepsilon})_i^n \\ (v_\varepsilon)_i^{n+1} = (v_\varepsilon)_i^n + \frac{\Delta t}{\Delta x} ((v_\varepsilon)_{i+1}^n - (v_\varepsilon)_i^n) - \frac{\Delta t}{\varepsilon + \Delta x} (S_{v_\varepsilon})_i^n \end{cases}$$

where

$$\begin{cases} (S_{u_\varepsilon})_i^n = h((v_\varepsilon)_{i-1}^n) - (u_\varepsilon)_{i-1}^n + (v_\varepsilon)_i^n - (v_\varepsilon)_{i-1}^n \\ (S_{v_\varepsilon})_i^n = h((v_\varepsilon)_i^n) - (u_\varepsilon)_i^n + (v_\varepsilon)_{i+1}^n - (v_\varepsilon)_i^n \end{cases}$$

Jin–Xin model with implicit equilibrium manifold

The limit of the scheme

$$(IAP) \quad \begin{cases} (u_\varepsilon)_i^{n+1} = (u_\varepsilon)_i^n - \frac{\Delta t}{\Delta x} ((u_\varepsilon)_i^n - (u_\varepsilon)_{i-1}^n) + \frac{\Delta t}{\varepsilon + \Delta x} (S_{u_\varepsilon})_i^n \\ (v_\varepsilon)_i^{n+1} = (v_\varepsilon)_i^n + \frac{\Delta t}{\Delta x} ((v_\varepsilon)_{i+1}^n - (v_\varepsilon)_i^n) - \frac{\Delta t}{\varepsilon + \Delta x} (S_{v_\varepsilon})_i^n \end{cases}$$

where

$$\begin{cases} (S_{u_\varepsilon})_i^n = h((v_\varepsilon)_{i-1}^n) - (u_\varepsilon)_{i-1}^n + (v_\varepsilon)_i^n - (v_\varepsilon)_{i-1}^n \\ (S_{v_\varepsilon})_i^n = h((v_\varepsilon)_i^n) - (u_\varepsilon)_i^n + (v_\varepsilon)_{i+1}^n - (v_\varepsilon)_i^n \end{cases}$$

is

$$(ILS) \quad \begin{cases} a_i^{n+1} = a_i^n - \frac{\Delta t}{\Delta x} (B(v_i^n) - B(v_{i-1}^n)) \\ v_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (h(v_i^n) - u_i^n) \\ u_i^{n+1} = a_i^{n+1} - v_i^{n+1} \end{cases}$$

Jin–Xin model with implicit equilibrium manifold

The limit scheme

$$(ILS) \quad \begin{cases} a_i^{n+1} = a_i^n - \frac{\Delta t}{\Delta x} (B(v_i^n) - B(v_{i-1}^n)) \\ v_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (h(v_i^n) - u_i^n) \\ u_i^{n+1} = a_i^{n+1} - v_i^{n+1} \end{cases}$$

must solve

$$\partial_t a + \partial_x (B \circ A^{-1})(a) = 0$$

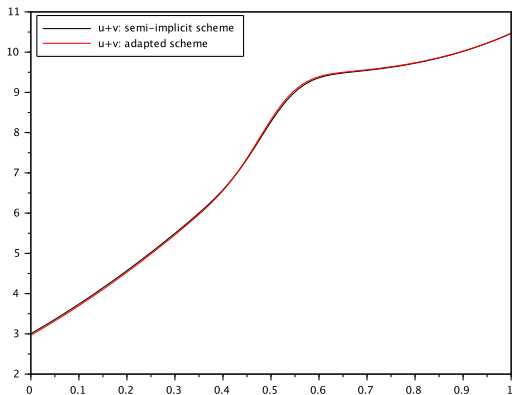
The second equation of the scheme corresponds to the numerical deviation from the equilibrium manifold

$$\mathcal{E} = \{u = h(v)\}$$

- Approximate Newton method
- Consistency in the sense of finite differences

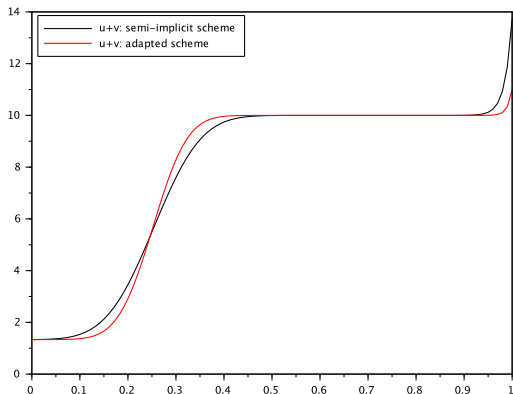
Semi-implicit scheme versus adapted scheme

Riemann problem with non-equilibrium right-hand boundary conditions: $\varepsilon = 1$



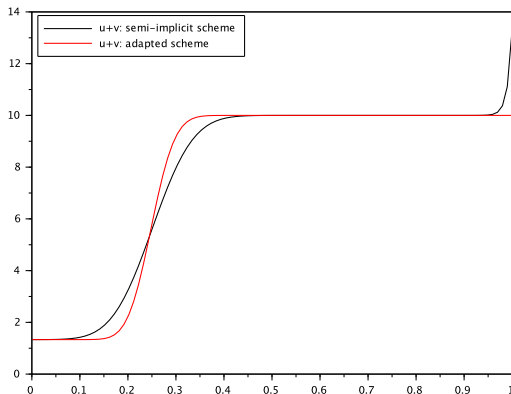
Semi-implicit scheme versus adapted scheme

Riemann problem with non-equilibrium right-hand boundary conditions: $\varepsilon = 10^{-2}$



Semi-implicit scheme versus adapted scheme

Riemann problem with non-equilibrium right-hand boundary conditions: $\varepsilon = 10^{-5}$



Jin–Xin model with implicit equilibrium manifold

- [Perthame, S., Tournus 2015]

Convergence of the model when $\varepsilon \rightarrow 0$ (even with $h(v, x)$)

- Adapted heterogeneous entropies
- BV_t ($\Rightarrow BV_x$) estimates \rightarrow strong convergence

- [S., Tournus 2015]

Construction of an explicit AP scheme

- which tends to an upwind scheme
- which approximately solve the implicit equilibrium
- Complete analysis for $\varepsilon > 0$

- Analysis of the limit scheme: convergence towards the entropy solution?
- Extension to more complex models

Boundaries and interfaces in asymptotics of hyperbolic systems of balance laws

Two distinct problems:

I. Jin–Xin model with implicit equilibrium manifold on a bounded domain

- Asymptotic behavior of boundary conditions
- Approximate but explicit computation of the equilibrium manifold

with B. Perthame and M. Tournus

II. Interface coupling of a systems of balance laws with its parabolic limit

- The Goldstein–Taylor model and the heat equation
- The p -system and the nonlinear heat equation
- Interface coupling/domain decomposition/two-scale discontinuous rate

with A.-C. Boulanger, C. Cancès, H. Mathis and K. Saleh

Interface coupling of a systems of balance laws with its parabolic limit

The coupling problem: $\varepsilon > 0$ at the left, $\varepsilon = 0$ at the right

$$x < 0$$

$$x = 0$$

$$x > 0$$

Hyperbolic system with relaxation

Associated parabolic limit

The Goldstein–Taylor model

$$\begin{cases} \varepsilon \partial_t v + \partial_x u = 0 \\ \varepsilon \partial_t u + a^2 \partial_x v = -\frac{\sigma}{\varepsilon} u \end{cases}$$

The heat equation

$$\begin{cases} \partial_t v - \frac{a^2}{\sigma} \partial_{xx} v = 0 \\ u = 0 \end{cases}$$

The p -system with damping

$$\begin{cases} \varepsilon \partial_t \tau - \partial_x u = 0 \\ \varepsilon \partial_t u + \partial_x P(\tau) = -\frac{\sigma}{\varepsilon} u \end{cases}$$

The nonlinear heat equation

$$\begin{cases} \partial_t \tau + \frac{1}{\sigma} \partial_{xx} P(\tau) = 0 \\ u = 0 \end{cases}$$

The Goldstein–Taylor model

Linear 2×2 system with linear dissipative term

$$(GT) \quad \begin{cases} \varepsilon \partial_t v + \partial_x u = 0 \\ \varepsilon \partial_t u + a^2 \partial_x v = -\frac{\sigma}{\varepsilon} u \end{cases}$$

- From the second equation: $u = -\varepsilon \frac{a^2}{\sigma} \partial_x v + \mathcal{O}(\varepsilon^2)$
- Inject in the first equation and divide by ε

When $\varepsilon \rightarrow 0$, one recover the linear heat equation

$$(HE) \quad \begin{cases} \partial_t v - \frac{a^2}{\sigma} \partial_{xx} v = 0 \\ u = 0 \end{cases}$$

Passage from a **hyperbolic regime** to a **parabolic regime**...

Design of asymptotic-preserving schemes

Construct a numerical scheme for system (GT) which becomes a numerical scheme for system (HE) when $\varepsilon \rightarrow 0$

- **Control of the numerical diffusion** compared to the parabolic limit
- From a **hyperbolic CFL condition** to a **parabolic CFL condition**

Here, we follow [Gosse, Toscani 2003]:

1. **Space localization** of the source term (well-balanced schemes, LeRoux et al.)
2. **Implicit discretization** of the source to guarantee the asymptotic stability

Design of asymptotic-preserving schemes

Construct a numerical scheme for system (GT) which becomes a numerical scheme for system (HE) when $\varepsilon \rightarrow 0$

- **Control of the numerical diffusion** compared to the parabolic limit
- From a **hyperbolic CFL condition** to a **parabolic CFL condition**

Here, we follow [Gosse, Toscani 2003]:

1. **Space localization** of the source term (well-balanced schemes, LeRoux et al.)
2. **Implicit discretization** of the source to guarantee the asymptotic stability

AP scheme: space localization of the source term

1. Given a mesh with Δt and Δx , approximate solution $(W_i^n)_{i,n} = (v_i^n, u_i^n)_{i,n}$:

$$\begin{cases} v_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_v(W_i^n, W_{i+1}^n) - F_v(W_{i-1}^n, W_i^n)) \\ u_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_u(W_i^n, W_{i+1}^n) - F_u(W_{i-1}^n, W_i^n)) + \Delta t S_i^n \end{cases}$$

or $u_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_u^-(W_i^n, W_{i+1}^n) - F_u^+(W_{i-1}^n, W_i^n))$

2. Solve at each interface the extended Riemann problem

$$\begin{cases} \partial_t v + \partial_x \frac{u}{\varepsilon} = 0 \\ \partial_t u + \partial_x \frac{a^2 v}{\varepsilon} + \frac{\sigma}{\varepsilon^2} u \partial_x \chi = 0 \\ \partial_t \chi = 0 \end{cases} \quad \text{with} \quad \begin{cases} W(0, x) = \begin{cases} W_i^n & \text{for } x < 0 \\ W_{i+1}^n & \text{for } x > 0 \end{cases} \\ \chi(0, x) = \begin{cases} \chi_l & \text{for } x < 0 \\ \chi_r & \text{for } x > 0 \end{cases} \end{cases}$$

with $\chi_r - \chi_l = \Delta x$

AP scheme: space localization of the source term

1. Given a mesh with Δt and Δx , approximate solution $(W_i^n)_{i,n} = (v_i^n, u_i^n)_{i,n}$:

$$\begin{cases} v_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_v(W_i^n, W_{i+1}^n) - F_v(W_{i-1}^n, W_i^n)) \\ u_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_u(W_i^n, W_{i+1}^n) - F_u(W_{i-1}^n, W_i^n)) + \Delta t S_i^n \end{cases}$$

or $u_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_u^-(W_i^n, W_{i+1}^n) - F_u^+(W_{i-1}^n, W_i^n))$

2. Solve at each interface the **extended Riemann problem**

$$\begin{cases} \partial_t v + \partial_x \frac{u}{\varepsilon} = 0 \\ \partial_t u + \partial_x \frac{a^2 v}{\varepsilon} + \frac{\sigma}{\varepsilon^2} u \partial_x \chi = 0 \\ \partial_t \chi = 0 \end{cases} \quad \text{with} \quad \begin{cases} W(0, x) = \begin{cases} W_i^n & \text{for } x < 0 \\ W_{i+1}^n & \text{for } x > 0 \end{cases} \\ \chi(0, x) = \begin{cases} \chi_l & \text{for } x < 0 \\ \chi_r & \text{for } x > 0 \end{cases} \end{cases}$$

with $\chi_r - \chi_l = \Delta x$

AP scheme: space localization of the source term

3. ... and obtain (remark the jump of v at $x = 0$)

$$W(t, x) = \begin{cases} W_l & \text{for } x/t < -a/\varepsilon \\ (\bar{v}^-, \bar{u}/K_\varepsilon) & \text{for } -a/\varepsilon < x/t < 0 \\ (\bar{v}^+, \bar{u}/K_\varepsilon) & \text{for } 0 < x/t < a/\varepsilon \\ W_r & \text{for } x/t > a/\varepsilon \end{cases}$$

with $K_\varepsilon = 1 + \frac{\sigma \Delta x}{2a\varepsilon}$ and

$$\bar{u}(W_l, W_r) = \frac{u_l + u_r}{2} - \frac{a}{2}(v_r - v_l)$$

$$\bar{v}^-(W_l, W_r) = v_l - \frac{1}{a}(\bar{u}(W_l, W_r)/K_\varepsilon - u_l)$$

$$\bar{v}^+(W_l, W_r) = v_r + \frac{1}{a}(\bar{u}(W_l, W_r)/K_\varepsilon - u_r)$$

AP scheme: space localization of the source term

4. The numerical scheme writes

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$

$$u_i^{n+1} = u_i^n - \frac{a^2 \Delta t}{\varepsilon \Delta x} [\bar{v}^-(W_i^n, W_{i+1}^n) - \bar{v}^+(W_{i-1}^n, W_i^n)]$$

or equivalently, with $\bar{v}(W_l, W_r) = \frac{v_l + v_r}{2} - \frac{1}{2a}(u_r - u_l)$,

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$

$$u_i^{n+1} = u_i^n - \frac{a^2 \Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{v}(W_i^n, W_{i+1}^n) - \bar{v}(W_{i-1}^n, W_i^n)] - \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon} u_i^n$$

AP scheme: space localization of the source term

4. The numerical scheme writes

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$
$$u_i^{n+1} = u_i^n - \frac{a^2 \Delta t}{\varepsilon \Delta x} [\bar{v}^-(W_i^n, W_{i+1}^n) - \bar{v}^+(W_{i-1}^n, W_i^n)]$$

or equivalently, with $\bar{v}(W_l, W_r) = \frac{v_l + v_r}{2} - \frac{1}{2a}(u_r - u_l)$,

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$
$$u_i^{n+1} = u_i^n - \frac{a^2 \Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{v}(W_i^n, W_{i+1}^n) - \bar{v}(W_{i-1}^n, W_i^n)] - \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon} u_i^n$$

BUT the resulting source term is explicitly approximated!

\implies CFL condition: $\Delta t \leq \frac{2\varepsilon}{\sigma} \left(\varepsilon + \frac{\sigma \Delta x}{2a} \right)$, which $\rightarrow 0$ when $\varepsilon \rightarrow 0$!

AP scheme: implicit modification of the source term

4. The classical well-balanced scheme:

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$
$$u_i^{n+1} = u_i^n - \frac{a^2 \Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{v}(W_i^n, W_{i+1}^n) - \bar{v}(W_{i-1}^n, W_i^n)] - \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon} u_i^n$$

5. Implicit discretization of the source term:

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$
$$u_i^{n+1} = u_i^n - \frac{a^2 \Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{v}(W_i^n, W_{i+1}^n) - \bar{v}(W_{i-1}^n, W_i^n)] - \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon} u_i^{n+1}$$

AP scheme: implicit modification of the source term

4. The classical well-balanced scheme:

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$
$$u_i^{n+1} = u_i^n - \frac{a^2 \Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{v}(W_i^n, W_{i+1}^n) - \bar{v}(W_{i-1}^n, W_i^n)] - \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon} u_i^n$$

5. Implicit discretization of the source term, but **explicit** formula:

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$
$$\left(1 + \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon}\right) \times u_i^{n+1} = u_i^n - \frac{a^2 \Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{v}(W_i^n, W_{i+1}^n) - \bar{v}(W_{i-1}^n, W_i^n)]$$

AP scheme

The final scheme (recall that $K_\varepsilon = 1 + \frac{\sigma \Delta x}{2a\varepsilon}$):

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$
$$u_i^{n+1} = \left(1 + \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon}\right)^{-1} \left(u_i^n - \frac{a^2 \Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{v}(W_i^n, W_{i+1}^n) - \bar{v}(W_{i-1}^n, W_i^n)]\right)$$

When $\varepsilon \rightarrow 0$, one obtains (except for $n = 0$):

$$v_i^{n+1} = v_i^n + \frac{a^2}{\sigma} \frac{\Delta t}{\Delta x^2} [v_{i+1}^n - 2v_i^n + v_{i-1}^n], \quad u_i^{n+1} = 0$$

Proposition ([Gosse, Toscani 2003])

This numerical scheme is *asymptotic preserving* since

- it is consistent with (GT) when $\varepsilon > 0$ and with (HE) when $\varepsilon = 0$
- it is \mathbb{L}^2 -stable under the CFL condition $\Delta t \leq \varepsilon \frac{\Delta x}{a} + \frac{\sigma}{2a^2} \Delta x^2$

AP scheme

The final scheme (recall that $K_\varepsilon = 1 + \frac{\sigma \Delta x}{2a\varepsilon}$):

$$v_i^{n+1} = v_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$
$$u_i^{n+1} = \left(1 + \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon}\right)^{-1} \left(u_i^n - \frac{a^2 \Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{v}(W_i^n, W_{i+1}^n) - \bar{v}(W_{i-1}^n, W_i^n)]\right)$$

When $\varepsilon \rightarrow 0$, one obtains (except for $n = 0$):

$$v_i^{n+1} = v_i^n + \frac{a^2}{\sigma} \frac{\Delta t}{\Delta x^2} [v_{i+1}^n - 2v_i^n + v_{i-1}^n], \quad u_i^{n+1} = 0$$

Proposition ([Gosse, Toscani 2003])

This numerical scheme is *asymptotic preserving* since

- it is consistent with (GT) when $\varepsilon > 0$ and with (HE) when $\varepsilon = 0$
- it is L^2 -stable under the CFL condition $\Delta t \leq \varepsilon \frac{\Delta x}{a} + \frac{\sigma}{2a^2} \Delta x^2$

The p -system with damping

The p -system with linear dissipative term, with $P' > 0$,

$$(PS) \quad \begin{cases} \varepsilon \partial_t \tau - \partial_x u = 0 \\ \varepsilon \partial_t u + \partial_x P(\tau) = -\frac{\sigma}{\varepsilon} u \end{cases}$$

- From the second equation: $u = -\varepsilon \frac{1}{\sigma} \partial_x P(\tau) + \mathcal{O}(\varepsilon^2)$
- Inject in the first equation and divide by ε

When $\varepsilon \rightarrow 0$, one recover the nonlinear heat equation

$$(NHE) \quad \begin{cases} \partial_t \tau + \frac{1}{\sigma} \partial_{xx} P(\tau) = 0 \\ u = 0 \end{cases}$$

Passage from a **hyperbolic regime** to a **parabolic regime**...

Design of asymptotic-preserving schemes

Construct a numerical scheme for system (PS) which becomes a numerical scheme for system (NHE) when $\varepsilon \rightarrow 0$

- **Control of the numerical diffusion** compared to the parabolic limit
- From a **hyperbolic CFL condition** to a **parabolic CFL condition**

Here, we extend [Gosse, Toscani 2003] to the **nonlinear** case:

1. Use **approximate Riemann solver** (HLL, relaxation...)
2. **Space localization** of the source term (well-balanced schemes, LeRoux et al.)
3. **Implicit discretization** of the source to guarantee the asymptotic stability

Note that schemes of [Chalons, Coquel, Godlewski, Raviart, S. 2010] and [Berthon, Turpault 2010] correspond to steps 1+2 (see also [Chalons, Girardin, Kokh 2013] for large time-step methods)

Design of asymptotic-preserving schemes

Construct a numerical scheme for system (PS) which becomes a numerical scheme for system (NHE) when $\varepsilon \rightarrow 0$

- **Control of the numerical diffusion** compared to the parabolic limit
- From a **hyperbolic CFL condition** to a **parabolic CFL condition**

Here, we extend [Gosse, Toscani 2003] to the **nonlinear** case:

1. Use **approximate Riemann solver** (HLL, relaxation. . .)
2. **Space localization** of the source term (well-balanced schemes, LeRoux et al.)
3. **Implicit discretization** of the source to guarantee the asymptotic stability

Note that schemes of [Chalons, Coquel, Godlewski, Raviart, S. 2010] and [Berthon, Turpault 2010] correspond to steps 1+2 (see also [Chalons, Girardin, Kokh 2013] for large time-step methods)

AP scheme: space localization of the source term

1. Given a mesh with Δt and Δx , approximate solution $(W_i^n)_{i,n} = (\tau_i^n, u_i^n)_{i,n}$:

$$\begin{cases} \tau_i^{n+1} = \tau_i^n - \frac{\Delta t}{\Delta x} (F_\tau(W_i^n, W_{i+1}^n) - F_\tau(W_{i-1}^n, W_i^n)) \\ u_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_u(W_i^n, W_{i+1}^n) - F_u(W_{i-1}^n, W_i^n)) + \Delta t S_i^n \end{cases}$$

or $u_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_u^-(W_i^n, W_{i+1}^n) - F_u^+(W_{i-1}^n, W_i^n))$

2. Solve at each interface the extended approximate Riemann problem

$$\begin{cases} \partial_t \tau - \partial_x \frac{u}{\varepsilon} = 0 \\ \partial_t u + \partial_x \frac{\pi}{\varepsilon} + \frac{\sigma}{\varepsilon^2} u \partial_x \chi = 0 \\ \partial_t \pi + \partial_x \frac{a^2}{\varepsilon} u = 0 \\ \partial_t \chi = 0 \end{cases} \quad \text{with} \quad \begin{cases} W(0, x) = \begin{cases} W_i^n & \text{for } x < 0 \\ W_{i+1}^n & \text{for } x > 0 \end{cases} \\ \chi(0, x) = \begin{cases} \chi_l & \text{for } x < 0 \\ \chi_r & \text{for } x > 0 \end{cases} \end{cases}$$

with $\chi_r - \chi_l = \Delta x$ and $a^2 > -P'(\tau)$

AP scheme: space localization of the source term

1. Given a mesh with Δt and Δx , approximate solution $(W_i^n)_{i,n} = (\tau_i^n, u_i^n)_{i,n}$:

$$\begin{cases} \tau_i^{n+1} = \tau_i^n - \frac{\Delta t}{\Delta x} (F_\tau(W_i^n, W_{i+1}^n) - F_\tau(W_{i-1}^n, W_i^n)) \\ u_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_u(W_i^n, W_{i+1}^n) - F_u(W_{i-1}^n, W_i^n)) + \Delta t S_i^n \end{cases}$$

or $u_i^{n+1} = v_i^n - \frac{\Delta t}{\Delta x} (F_u^-(W_i^n, W_{i+1}^n) - F_u^+(W_{i-1}^n, W_i^n))$

2. Solve at each interface the extended approximate Riemann problem

$$\begin{cases} \partial_t \tau - \partial_x \frac{u}{\varepsilon} = 0 \\ \partial_t u + \partial_x \frac{\pi}{\varepsilon} + \frac{\sigma}{\varepsilon^2} u \partial_x \chi = 0 \\ \partial_t \pi + \partial_x \frac{a^2}{\varepsilon} u = 0 \\ \partial_t \chi = 0 \end{cases} \quad \text{with} \quad \begin{cases} W(0, x) = \begin{cases} W_i^n & \text{for } x < 0 \\ W_{i+1}^n & \text{for } x > 0 \end{cases} \\ \chi(0, x) = \begin{cases} \chi_l & \text{for } x < 0 \\ \chi_r & \text{for } x > 0 \end{cases} \end{cases}$$

with $\chi_r - \chi_l = \Delta x$ and $a^2 > -P'(\tau)$

AP scheme

Same calculations + Implicit discretization of the source term...

$$\tau_i^{n+1} = \tau_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$

$$u_i^{n+1} = \left(1 + \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon}\right)^{-1} \left(u_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{\pi}(W_i^n, W_{i+1}^n) - \bar{\pi}(W_{i-1}^n, W_i^n)]\right)$$

When $\varepsilon \rightarrow 0$, one obtains (except for $n = 0$):

$$\tau_i^{n+1} = \tau_i^n - \frac{\Delta t}{\sigma \Delta x^2} [P(\tau_{i+1}^n) - 2P(\tau_i^n) + P(\tau_{i-1}^n)] \quad , \quad u_i^{n+1} = 0$$

Proposition ([Boulanger, Cancès, Mathis, Saleh, S. 2012])

This numerical scheme is *asymptotic preserving* since

- it is *consistent* with (PS) when $\varepsilon > 0$ and with (NHE) when $\varepsilon = 0$
- it is *positive and entropy-stable* under the CFL condition, with $a^2 > -P'(\tau)$,

$$\Delta t \leq \varepsilon \frac{\Delta x}{2a} + \frac{\sigma}{4a^2} \Delta x^2$$

AP scheme

Same calculations + Implicit discretization of the source term...

$$\tau_i^{n+1} = \tau_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{u}(W_i^n, W_{i+1}^n) - \bar{u}(W_{i-1}^n, W_i^n)]$$

$$u_i^{n+1} = \left(1 + \frac{\sigma \Delta t}{\varepsilon^2 K_\varepsilon}\right)^{-1} \left(u_i^n - \frac{\Delta t}{\varepsilon K_\varepsilon \Delta x} [\bar{\pi}(W_i^n, W_{i+1}^n) - \bar{\pi}(W_{i-1}^n, W_i^n)]\right)$$

When $\varepsilon \rightarrow 0$, one obtains (except for $n = 0$):

$$\tau_i^{n+1} = \tau_i^n - \frac{\Delta t}{\sigma \Delta x^2} [P(\tau_{i+1}^n) - 2P(\tau_i^n) + P(\tau_{i-1}^n)] \quad , \quad u_i^{n+1} = 0$$

Proposition ([Boulanger, Cancès, Mathis, Saleh, S. 2012])

This numerical scheme is *asymptotic preserving* since

- it is *consistent* with (PS) when $\varepsilon > 0$ and with (NHE) when $\varepsilon = 0$
- it is *positive* and *entropy-stable* under the CFL condition, with $a^2 > -P'(\tau)$,

$$\Delta t \leq \varepsilon \frac{\Delta x}{2a} + \frac{\sigma}{4a^2} \Delta x^2$$

The coupling problem

The coupling problem: $\varepsilon > 0$ at the left, $\varepsilon = 0$ at the right

$$x < 0$$

$$x = 0$$

$$x > 0$$

The Goldstein–Taylor model

$$\begin{cases} \partial_t v + \frac{1}{\varepsilon} \partial_x u = 0 \\ \partial_t u + \frac{a^2}{\varepsilon} \partial_x v = -\frac{\sigma}{\varepsilon^2} u \end{cases}$$

The heat equation

$$\begin{cases} \partial_t v - \frac{a^2}{\sigma} \partial_{xx} v = 0 \\ u = 0 \end{cases}$$

Basic requirements:

- When $\varepsilon \gg 1$
Hyperbolic solution at the left and the parabolic solution at the right
- When $\varepsilon \ll 1$
Hyperbolic and parabolic are similar, the coupling should also be

⇒ Mixing of BC's

⇒ Recover the parabolic scheme when $\varepsilon \rightarrow 0$

The coupling problem: a first simple idea

Coupling conditions, from **parabolic/parabolic** coupling:

- **Continuity of the unknown:**

$$v(t, 0^-) = v(t, 0^+)$$

- **Continuity of the flux**, i.e. global conservation of v :

$$\frac{u}{\varepsilon}(t, 0^-) = -\frac{a^2}{\sigma} \partial_x v(t, 0^+)$$

At the numerical interface of coupling $x_{1/2} = 0$ between cells 0 and 1:

- Ghost-cell method:

$$W_0^n = (v_0^n, u_0^n) \quad \Big| \quad W_1^n = (v_1^n, 0)$$

- Compute the **common flux** for v using **the hyperbolic model**:

$$F_{1/2}^n = F_{\text{Hyp}}(W_0^n, (v_1^n, 0)) = \frac{1}{\varepsilon K_\varepsilon} \bar{u}(W_0^n, (v_1^n, 0))$$

The coupling problem: a first simple idea

Coupling conditions, from **parabolic/parabolic** coupling:

- **Continuity of the unknown:**

$$v(t, 0^-) = v(t, 0^+)$$

- **Continuity of the flux**, i.e. global conservation of v :

$$\frac{u}{\varepsilon}(t, 0^-) = -\frac{a^2}{\sigma} \partial_x v(t, 0^+)$$

At the numerical interface of coupling $x_{1/2} = 0$ between cells **0** and **1**:

- Ghost-cell method:

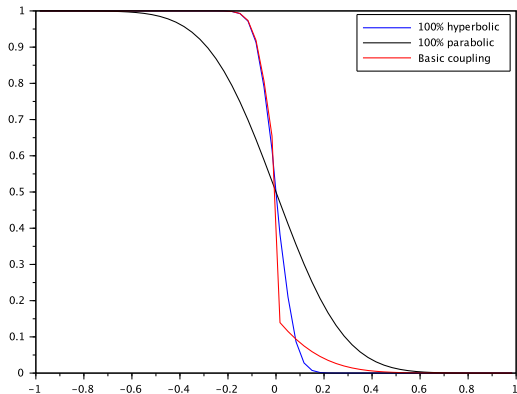
$$W_0^n = (v_0^n, u_0^n) \quad \Big| \quad W_1^n = (v_1^n, 0)$$

- Compute the **common flux** for v using **the hyperbolic model**:

$$F_{1/2}^n = F_{\text{Hyp}}(W_0^n, (v_1^n, 0)) = \frac{1}{\varepsilon K_\varepsilon} \bar{u}(W_0^n, (v_1^n, 0))$$

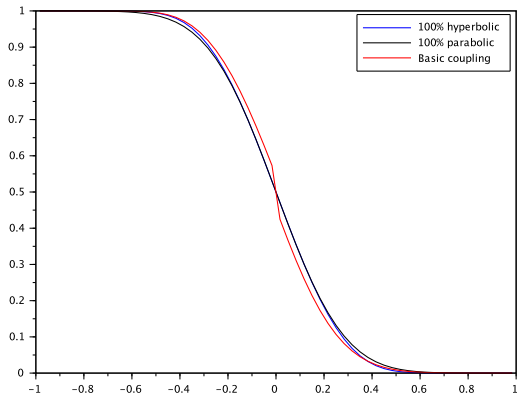
The coupling problem: a first simple idea

Riemann problem with Dirichlet boundary conditions: $\varepsilon = 1$



The coupling problem: a first simple idea

Riemann problem with Dirichlet boundary conditions: $\varepsilon = 0.1$



The coupling problem: partial Riemann problem

Coupling conditions, from **parabolic/parabolic** coupling:

- **Continuity of the unknown:**

$$v(t, 0^-) = v(t, 0^+)$$

- **Continuity of the flux**, i.e. global conservation of v :

$$\frac{u}{\varepsilon}(t, 0^-) = -\frac{a^2}{\sigma} \partial_x v(t, 0^+)$$

At the numerical interface of coupling $x_{1/2} = 0$:

- Solve a **partial Riemann problem** at the left:

$$u_{1/2}^* - u_0^n = a(v_0^n - v_{1/2}^*)$$

- **Continuity of the flux:**

$$\frac{u_{1/2}^*}{\varepsilon} = -\frac{a^2}{\sigma} \frac{v_1^n - v_{1/2}^*}{\Delta x/2}$$

The coupling problem: partial Riemann problem

Coupling conditions, from **parabolic/parabolic** coupling:

- **Continuity of the unknown:**

$$v(t, 0^-) = v(t, 0^+)$$

- **Continuity of the flux**, i.e. global conservation of v :

$$\frac{u}{\varepsilon}(t, 0^-) = -\frac{a^2}{\sigma} \partial_x v(t, 0^+)$$

At the numerical interface of coupling $x_{1/2} = 0$:

- Solve a **partial Riemann problem** at the left:

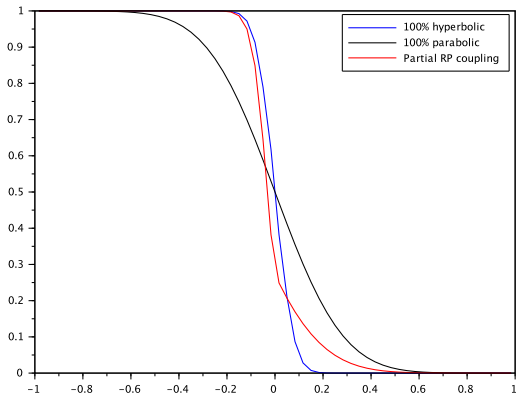
$$u_{1/2}^* - u_0^n = a(v_0^n - v_{1/2}^*)$$

- **Continuity of the flux:**

$$\frac{u_{1/2}^*}{\varepsilon} = -\frac{a^2}{\sigma} \frac{v_1^n - v_{1/2}^*}{\Delta x/2}$$

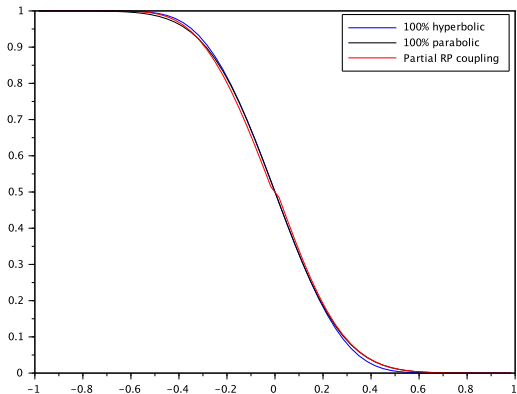
The coupling problem: partial Riemann problem

Riemann problem with Dirichlet boundary conditions: $\varepsilon = 1$



The coupling problem: partial Riemann problem

Riemann problem with Dirichlet boundary conditions: $\varepsilon = 0.1$



The coupling problem for the p -system with damping

The coupling problem: $\varepsilon > 0$ at the left, $\varepsilon = 0$ at the right

$$x < 0$$

$$x = 0$$

$$x > 0$$

The p -system with damping

$$\begin{cases} \partial_t \tau - \frac{1}{\varepsilon} \partial_x u = 0 \\ \partial_t u + \frac{1}{\varepsilon} \partial_x P(\tau) = -\frac{\sigma}{\varepsilon^2} u \end{cases}$$

The nonlinear heat equation

$$\begin{cases} \partial_t \tau + \frac{a^2}{\sigma} \partial_{xx} P(\tau) = 0 \\ u = 0 \end{cases}$$

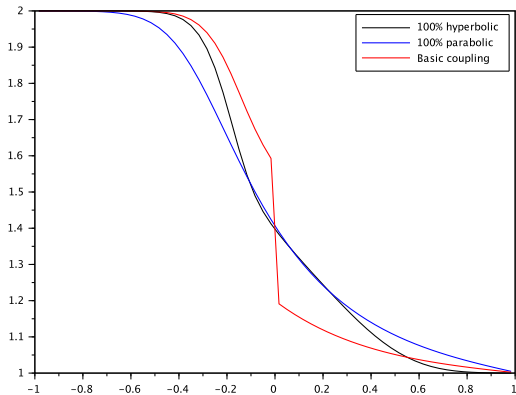
Same requirements and ideas...

- First idea: use the AP numerical flux
- Second idea: use a partial Riemann problem

Same consequences!

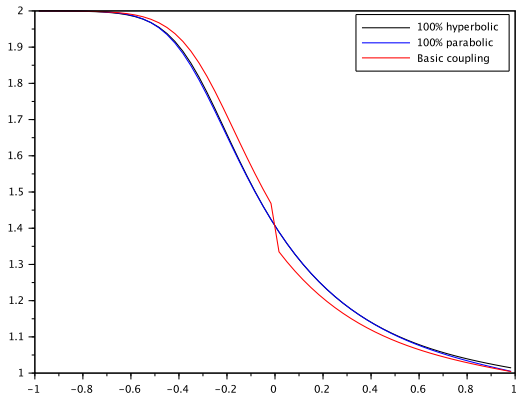
The coupling problem: using the AP flux

Riemann problem with Dirichlet boundary conditions: $\varepsilon = 0.5$



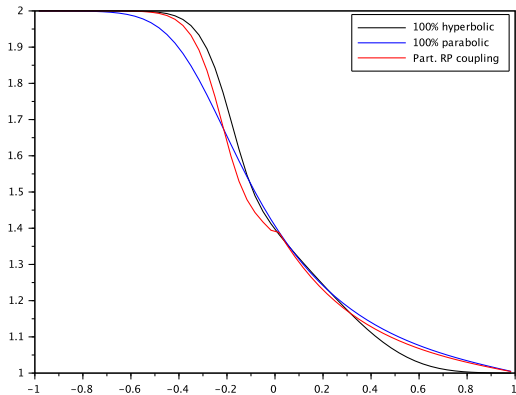
The coupling problem: using the AP flux

Riemann problem with Dirichlet boundary conditions: $\varepsilon = 0.1$



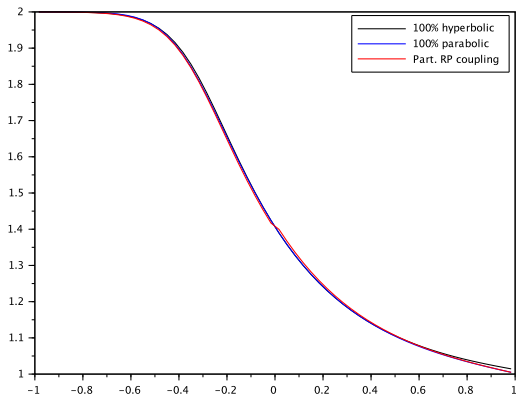
The coupling problem: partial Riemann problem

Riemann problem with Dirichlet boundary conditions: $\varepsilon = 0.5$



The coupling problem: partial Riemann problem

Riemann problem with Dirichlet boundary conditions: $\varepsilon = 0.1$



Interfacial coupling and parabolic limit

- Goldstein–Taylor model and the p -system with damping
- Construction of asymptotic preserving schemes
- Interfacial coupling between two numerical schemes which perfectly match
 1. Direct use of the numerical flux of the AP scheme
 2. Partial Riemann problem in the hyperbolic part

But...

- What are the rigorous coupling conditions?
- How to extend this coupling to more complex systems?
- What happens when the two numerical schemes do not perfectly match?

[Salvarani 1999], [Salvarani, Golse 2007], [Golse, Jin, Levermore 2003],
[Lemou, Méhats 2012], [Vasseur 2012], [Coquel, Jin, Liu, Wang 2015]...

Interfacial coupling and parabolic limit

- Goldstein–Taylor model and the p -system with damping
- Construction of asymptotic preserving schemes
- Interfacial coupling between two numerical schemes which perfectly match
 1. Direct use of the numerical flux of the AP scheme
 2. Partial Riemann problem in the hyperbolic part

But...

- What are the rigorous coupling conditions?
- How to extend this coupling to more complex systems?
- What happens when the two numerical schemes do not perfectly match?

[Salvarani 1999], [Salvarani, Golse 2007], [Golse, Jin, Levermore 2003],
[Lemou, Méhats 2012], [Vasseur 2012], [Coquel, Jin, Liu, Wang 2015]...

Than you for your attention

